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## Main

Range of product	Altivar Process ATV600
Product or component type	Variable speed drive
Product specific application	Process and utilities
Device short name	ATV630
Variant	Standard version
Product destination	Asynchronous motors Synchronous motors
EMC filter	Integrated conforming to EN/IEC 61800-3 category C3
IP degree of protection	IP21 conforming to IEC 61800-5-1 IP21 conforming to IEC 60529
Type of cooling	Forced convection
Supply frequency	50...60 Hz - 5...5 %
Network number of phases	3 phases
[Us] rated supply voltage	380...440 V - 15...10 %
Motor power kW	200 kW (normal duty) 160 kW (heavy duty)
Line current	349 A at 400 V (normal duty) 286 A at 400 V (heavy duty) 369 A at 380 V (normal duty) 302 A at 380 V (heavy duty)
Prospective line I <sub>sc</sub>	50 kA
Apparent power	242 kVA at 440 V (normal duty) 198 kVA at 440 V (heavy duty)
Continuous output current	370 A at 2.5 kHz for normal duty 302 A at 2.5 kHz for heavy duty
Maximum transient current	407 A during 60 s (normal duty) 453 A during 60 s (heavy duty)
Asynchronous motor control profile	Variable torque standard Constant torque standard Optimized torque mode
Synchronous motor control profile	Permanent magnet motor Synchronous reluctance motor
Output frequency	0.0001...0.5 kHz
Speed drive output frequency	0.1...599 Hz
Nominal switching frequency	2.5 kHz
Switching frequency	2.5...8 kHz with derating factor 2...8 kHz adjustable
Safety function	STO (safe torque off) SIL 3
Discrete input logic	16 preset speeds

Communication port protocol	Modbus TCP Modbus serial Ethernet
Option card	Slot A: communication module, Profibus DP V1 Slot A: communication module, Profinet Slot A: communication module, DeviceNet Slot A: communication module, Modbus TCP/ EtherNet/IP Slot A: communication module, CANopen daisy chain RJ45 Slot A: communication module, CANopen SUB-D 9 Slot A: communication module, CANopen screw terminals Slot A/slot B: digital and analog I/O extension module Slot A/slot B: output relay extension module Slot A: communication module, Ethernet IP/Modbus TCP/MD-Link Communication module, BACnet MS/TP Communication module, Ethernet Powerlink

## Complementary

Output voltage	$\leq$ power supply voltage
Permissible temporary current boost	1.1 x $I_n$ during 60 s (normal duty) 1.5 x $I_n$ during 60 s (heavy duty)
Motor slip compensation	Not available in permanent magnet motor law Adjustable Automatic whatever the load Can be suppressed
Acceleration and deceleration ramps	Linear adjustable separately from 0.01...9999 s
Braking to standstill	By DC injection
Protection type	Thermal protection: motor Safe torque off: motor Motor phase break: motor Thermal protection: drive Safe torque off: drive Overheating: drive Overcurrent between output phases and earth: drive Overload of output voltage: drive Short-circuit protection: drive Motor phase break: drive Overvoltages on the DC bus: drive Line supply overvoltage: drive Line supply undervoltage: drive Line supply phase loss: drive Overspeed: drive Break on the control circuit: drive
Frequency resolution	Display unit: 0.1 Hz Analog input: 0.012/50 Hz
Electrical connection	Control: removable screw terminals 0.5...1.5 mm <sup>2</sup> Line side: M12 bar - 2 cables 3 x 120 mm <sup>2</sup> minimum per phase (normal duty) Line side: M12 bar - 3 cables 3 x 70 mm <sup>2</sup> minimum per phase (normal duty) Line side: M12 bar - 3 cables 3 x 185 mm <sup>2</sup> maximum per phase (normal duty) Line side: M12 bar - 4 cables 3 x 120 mm <sup>2</sup> maximum per phase (normal duty) Motor: M12 bar - 2 cables 3 x 120 mm <sup>2</sup> minimum per phase (normal duty) Motor: M12 bar - 3 cables 3 x 70 mm <sup>2</sup> minimum per phase (normal duty) Motor: M12 bar - 3 cables 3 x 185 mm <sup>2</sup> maximum per phase (normal duty) Motor: M12 bar - 4 cables 3 x 120 mm <sup>2</sup> maximum per phase (normal duty) Line side: M12 bar - 2 cables 3 x 95 mm <sup>2</sup> minimum per phase (heavy duty) Line side: M12 bar - 3 cables 3 x 185 mm <sup>2</sup> maximum per phase (heavy duty) Line side: M12 bar - 4 cables 3 x 120 mm <sup>2</sup> maximum per phase (heavy duty) Motor: M12 bar - 1 cables 3 x 185 mm <sup>2</sup> minimum per phase (heavy duty) Motor: M12 bar - 2 cables 3 x 95 mm <sup>2</sup> minimum per phase (heavy duty) Motor: M12 bar - 3 cables 3 x 185 mm <sup>2</sup> maximum per phase (heavy duty) Motor: M12 bar - 4 cables 3 x 120 mm <sup>2</sup> maximum per phase (heavy duty)
Connector type	RJ45 (on the remote graphic terminal) for Ethernet/Modbus TCP RJ45 (on the remote graphic terminal) for Modbus serial
Physical interface	2-wire RS 485 for Modbus serial
Transmission frame	RTU for Modbus serial
Transmission rate	10/100 Mbit/s for Ethernet IP/Modbus TCP 4.8, 9.6, 19.2, 38.4 kbit/s for Modbus serial
Exchange mode	Half duplex, full duplex, autonegotiation Ethernet/Modbus TCP

Data format	8 bits, configurable odd, even or no parity for Modbus serial
Type of polarization	No impedance for Modbus serial
Number of addresses	1...247 for Modbus serial
Method of access	Slave Modbus TCP
Supply	External supply for digital inputs: 24 V DC (19...30 V), <1.25 mA, protection type: overload and short-circuit protection Internal supply for reference potentiometer (1 to 10 kOhm): 10.5 V DC +/- 5 %, <10 mA, protection type: overload and short-circuit protection Internal supply for digital inputs and STO: 24 V DC (21...27 V), <200 mA, protection type: overload and short-circuit protection
Local signalling	3 LEDs for local diagnostic 3 LEDs (dual colour) for embedded communication status 4 LEDs (dual colour) for communication module status 1 LED (red) for presence of voltage
Width	600 mm
Height	2150 mm
Depth	605 mm
Net weight	400 kg
Analogue input number	3
Analogue input type	AI1, AI2, AI3 software-configurable voltage: 0...10 V DC, impedance: 30 kOhm, resolution 12 bits AI1, AI2, AI3 software-configurable current: 0...20 mA/4...20 mA, impedance: 250 Ohm, resolution 12 bits
Discrete input number	8
Discrete input type	DI1...DI6 programmable, 24 V DC (<= 30 V), impedance: 3.5 kOhm DI5, DI6 programmable as pulse input: 0...30 kHz, 24 V DC (<= 30 V) STOA, STOB safe torque off, 24 V DC (<= 30 V), impedance: > 2.2 kOhm
Input compatibility	DI1...DI6: discrete input level 1 PLC conforming to EN/IEC 61131-2 DI5, DI6: discrete input level 1 PLC conforming to IEC 65A-68 STOA, STOB: discrete input level 1 PLC conforming to EN/IEC 61131-2
Discrete input logic	Positive logic (source) (DI1...DI6), < 5 V (state 0), > 11 V (state 1) Negative logic (sink) (DI1...DI6), > 16 V (state 0), < 10 V (state 1) Positive logic (source) (DI5, DI6), < 0.6 V (state 0), > 2.5 V (state 1) Positive logic (source) (STOA, STOB), < 5 V (state 0), > 11 V (state 1)
Analogue output number	2
Analogue output type	Software-configurable voltage AO1, AO2: 0...10 V DC impedance 470 Ohm, resolution 10 bits Software-configurable current AO1, AO2: 0...20 mA, resolution 10 bits
Sampling duration	2 Ms +/- 0.5 ms (DI1...DI4) - discrete input 5 Ms +/- 1 ms (DI5, DI6) - discrete input 5 Ms +/- 0.1 ms (AI1, AI2, AI3) - analog input 10 ms +/- 1 ms (AO1) - analog output
Accuracy	+/- 0.6 % AI1, AI2, AI3 for a temperature variation 60 °C analog input +/- 1 % AO1, AO2 for a temperature variation 60 °C analog output
Linearity error	AI1, AI2, AI3: +/- 0.15 % of maximum value for analog input AO1, AO2: +/- 0.2 % for analog output
Relay output number	3
Relay output type	Configurable relay logic R1: fault relay NO/NC electrical durability 100000 cycles Configurable relay logic R2: sequence relay NO electrical durability 100000 cycles Configurable relay logic R3: sequence relay NO electrical durability 100000 cycles
Refresh time	Relay output (R1, R2, R3): 5 ms (+/- 0.5 ms)
Minimum switching current	Relay output R1, R2, R3: 5 mA at 24 V DC
Maximum switching current	Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 250 V AC Relay output R1, R2, R3 on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 250 V AC Relay output R1, R2, R3 on inductive load, cos phi = 0.4 and L/R = 7 ms: 2 A at 30 V DC
Isolation	Between power and control terminals

Variable speed drive application selection	Compressor centrifugal Building - HVAC Other application Food and beverage processing Fan Mining mineral and metal Pump Mining mineral and metal Fan Oil and gas Other application Water and waste water Screw compressor Building - HVAC Pump Food and beverage processing Fan Food and beverage processing Atomization Food and beverage processing Electro submersible pump (ESP) Oil and gas Water injection pump Oil and gas Jet fuel pump Oil and gas Compressor for refinery Oil and gas Centrifuge pump Water and waste water Positive displacement pump Water and waste water Electro submersible pump (ESP) Water and waste water Screw pump Water and waste water Lobe compressor Water and waste water Screw compressor Water and waste water Compressor centrifugal Water and waste water Fan Water and waste water Conveyor Water and waste water Mixer Water and waste water
Motor power range AC-3	110...220 kW at 380...440 V 3 phases
Mounting mode	Floor-standing

## Environment

Insulation resistance	> 1 MOhm 500 V DC for 1 minute to earth
Noise level	70 dB conforming to 86/188/EEC
Power dissipation in W	4380 W, switching frequency 2.5 kHz (normal duty) 3380 W, switching frequency 2.5 kHz (heavy duty)
Volume of cooling air	1300 m <sup>3</sup> /h
Operating position	Vertical +/- 10 degree
Maximum THDI	<48 % full load conforming to IEC 61000-3-12
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6
Pollution degree	2 conforming to EN/IEC 61800-5-1
Vibration resistance	1.5 mm peak to peak (f= 2...13 Hz) conforming to IEC 60068-2-6 1 gn (f= 13...200 Hz) conforming to IEC 60068-2-6
Shock resistance	15 gn for 11 ms conforming to IEC 60068-2-27
Relative humidity	5...95 % without condensation conforming to IEC 60068-2-3
Ambient air temperature for operation	-15...40 °C (without derating) 40...50 °C (with derating factor)
Ambient air temperature for storage	-40...70 °C
Operating altitude	<= 1000 m without derating 1000...4800 m with current derating 1 % per 100 m
Environmental characteristic	Chemical pollution resistance class 3C3 conforming to EN/IEC 60721-3-3 Dust pollution resistance class 3S3 conforming to EN/IEC 60721-3-3
Standards	UL 508C EN/IEC 61800-3 Environment 2 category C3 EN/IEC 61800-3 EN/IEC 61800-5-1 IEC 61000-3-12 IEC 60721-3 IEC 61508 IEC 13849-1
Product certifications	TÜV CSA ATEX zone 2/22 ATEX INERIS REACH
Marking	CE

## Packing Units

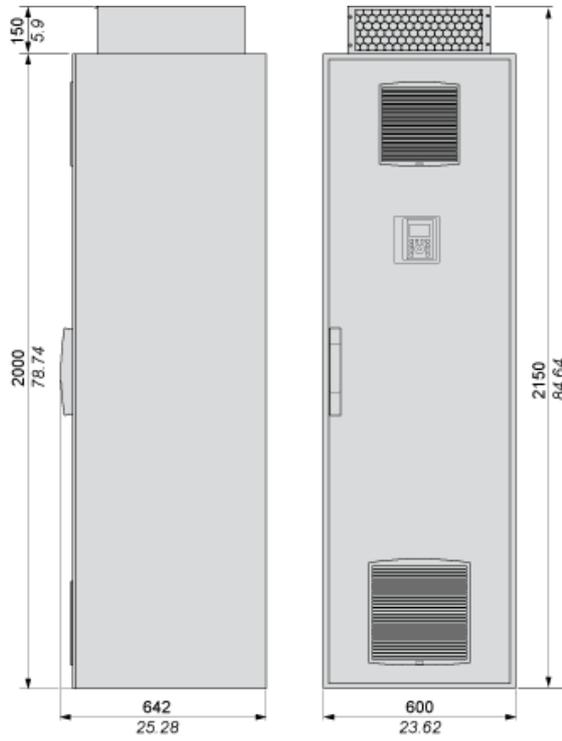
Package 1 Weight	485.000 kg
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## Offer Sustainability

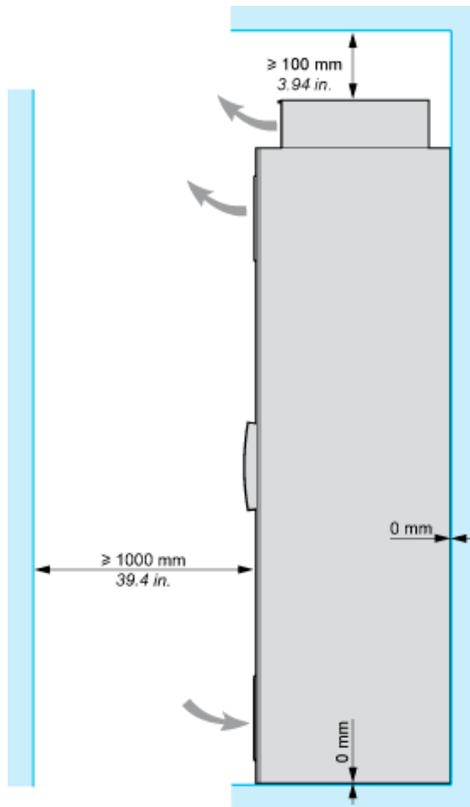
Sustainable offer status	Green Premium product
REACH Regulation	<a href="#">REACH Declaration</a>
EU RoHS Directive	Pro-active compliance (Product out of EU RoHS legal scope) <a href="#">EU RoHS Declaration</a>
Mercury free	Yes
RoHS exemption information	<a href="#">Yes</a>
China RoHS Regulation	<a href="#">China RoHS Declaration</a>
Environmental Disclosure	<a href="#">Product Environmental Profile</a>
Circularity Profile	<a href="#">End Of Life Information</a>
WEEE	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

Dimensions

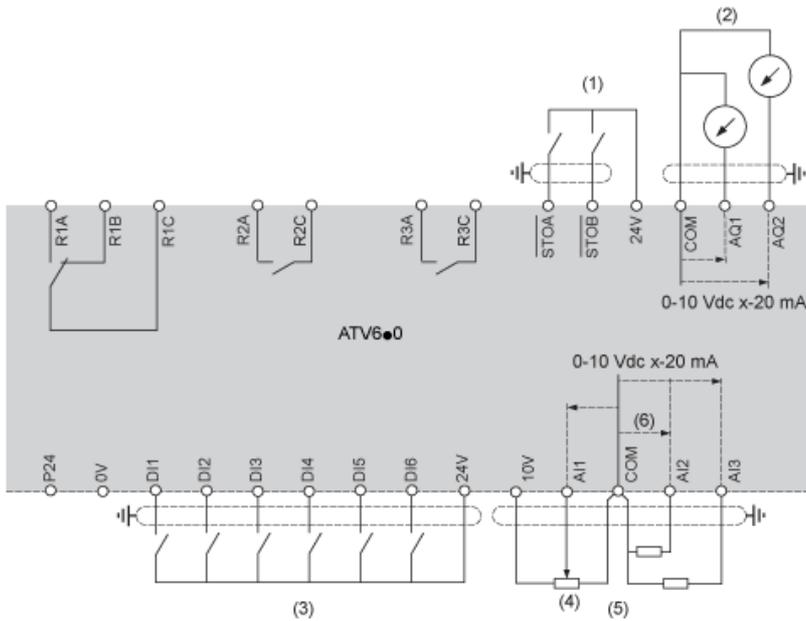
Right and Front Views



Clearances



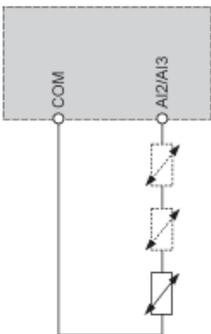




- (1) Safe Torque Off
- (2) Analog Output
- (3) Digital Input
- (4) Reference potentiometer
- (5) Analog Input
- R1A, Fault relay
- R1B,
- R1C :
- R2A, Sequence relay
- R2C :
- R3A, Sequence relay
- R3C :

### Sensor Connection

It is possible to connect either 1 or 3 sensors on terminals AI2 or AI3.

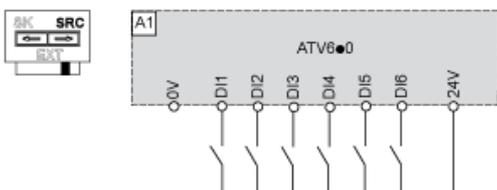


### Sink / Source Switch Configuration

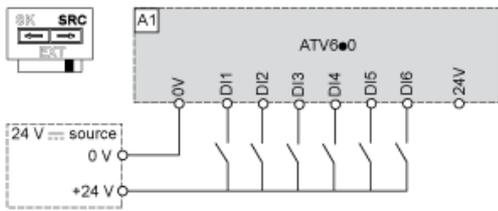
The switch is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

- Set the switch to Source (factory setting) if using PLC outputs with PNP transistors.
- Set the switch to Ext if using PLC outputs with NPN transistors.

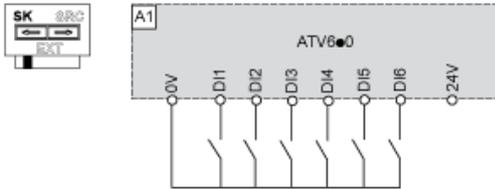
### Switch Set to SRC (Source) Position Using the Output Power Supply for the Digital Inputs



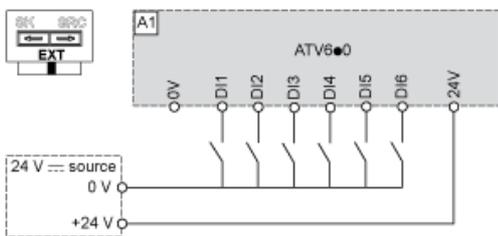
### Switch Set to SRC (Source) Position and Use of an External Power Supply for the DIs



### Switch Set to SK (Sink) Position Using the Output Power Supply for the Digital Inputs

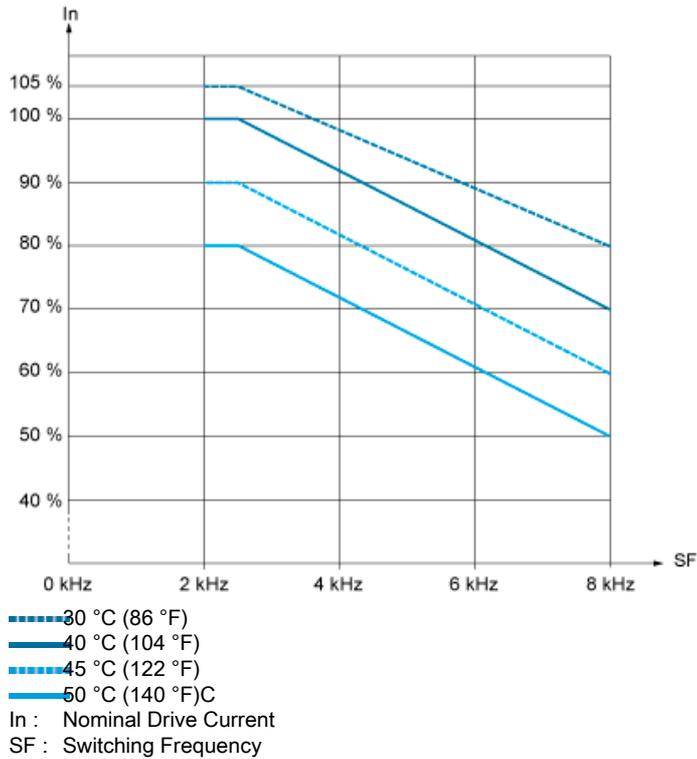


### Switch Set to EXT Position Using an External Power Supply for the DIs



Derating Curves

Normal Duty



Heavy Duty

